

Finite-Valued Streaming String Transducers

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based on joint work with

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Finite Automata and Languages

Finite automata define a very robust class of languages

- ▶ many equivalent automaton models: deterministic, nondeterministic, 2-way, ϵ -transitions
- ▶ various other representations: regular expressions, MSO logic, monoids
- ▶ excellent closure-properties: Boolean operations, projection, homomorphisms, reversal, ...
- ▶ many interesting problems decidable: equivalence, emptiness, universality, ...

(Word-)Transductions

A **(word-)transduction** is a relation $R \subseteq \Sigma^* \times \Sigma^*$ between words.

Examples.

reverse	$abaabba \mapsto abbaaba$
copy	$abaabba \mapsto abbaabaabbaaba$
sort	$abaabba \mapsto aaaabbb$
delete <i>as</i>	$abaabba \mapsto bbb$
infix	$abb \mapsto \varepsilon, a, ab, abb$
rotate	$abb \mapsto abb, bba, bab$
iterate	$abb \mapsto abb, abbabb, abbabbabb, \dots$

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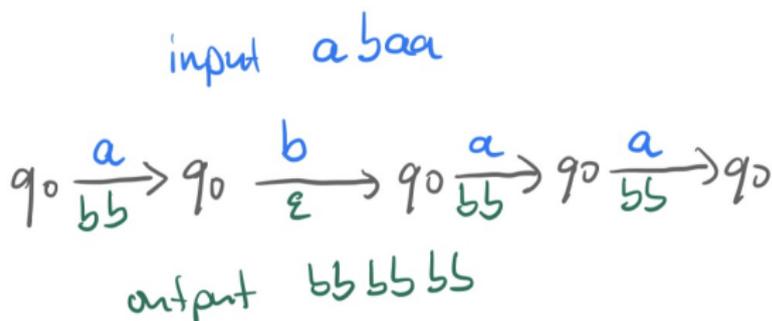
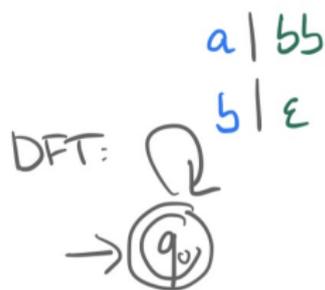
Transductions are defined by (finite) transducers (automata with output). Unlike for automata, the defined classes of transductions vary by transducer model.

Transducer Models

Finite Transducers

A **finite transducer (FT)** is a finite automaton that additionally has output words on its transitions.

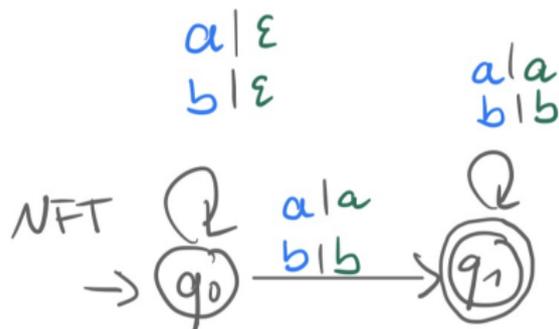
Example. Deterministic FT.



Finite Transducers

A **finite transducer (FT)** is a finite automaton that additionally has output words on its transitions.

Example. Nondeterministic FT.



"non-empty suffix"

Properties of Finite Transducers

- ▶ DFTs define functions, NFTs can define relations.
- ▶ It is decidable whether an NFT defines a function (Schützenberger 1975).
- ▶ Equivalence is decidable for DFTs (Blattner, Head 1979).
- ▶ Equivalence is undecidable for NFTs (Fischer, Rosenberg 1968).
- ▶ Fewer closure-properties than finite automata, e.g., FTs are not closed under intersection.

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Drawback

- ▶ FTs are limited in their expressiveness, for example “copy”, “reverse”, “sort”, ... are not definable.
- ▶ Is there a more expressive model?

2-way Finite Transducers

A **2-way finite transducer (2-FT)** can move left and right on its input tape and produce output from left to right.

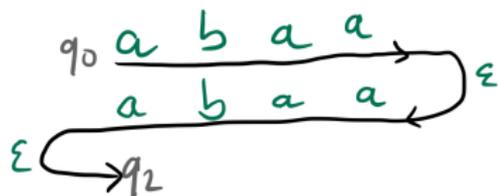
Example. Deterministic 2-FT.

"copy and reverse"

$a|a, \Delta$ $a|a, \Delta$
 $b|b, \triangleright$ $b|\epsilon, \Delta$



$\vdash a b a a \vdash$

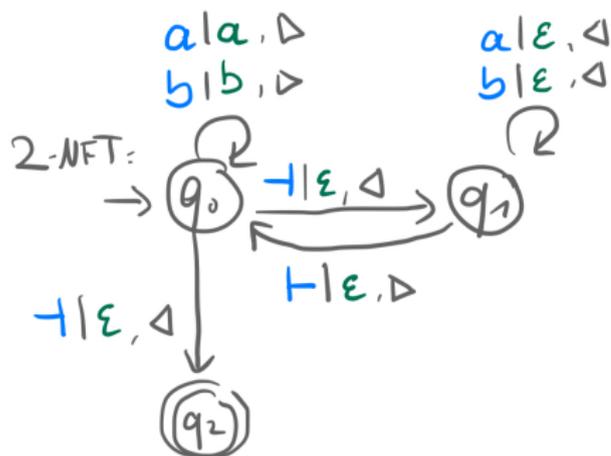


input: $\vdash a b a a \vdash$
output: $a b a a a a b a$

2-way Finite Transducers

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Example. Nondeterministic 2-FT.



“iterate”

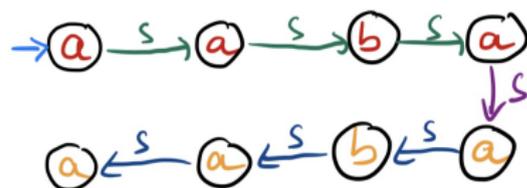
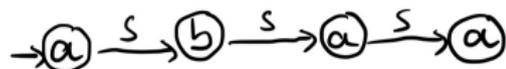
$$u \mapsto \{u^n \mid n \geq 1\}$$

MSO Transductions

A **monadic second order logic transduction (MSOT)** takes a fixed number of copies of the universe of the input structure, and defines the relations of the output structure by MSO formulas.

Example. Deterministic 2-FT.

"copy and reverse"



$$\varphi_s^{1,1}(x,y) := S(x,y)$$

$$\varphi_s^{1,2}(x,y) := x=y \wedge \text{last}(x)$$

$$\varphi_s^{2,2}(x,y) := S(y,x)$$

$$\varphi_s^{2,1}(x,y) := \perp$$

$$\varphi_{\text{init}}^1(x) := \text{init}(x), \quad \varphi_{\text{init}}^2(x) := \perp$$

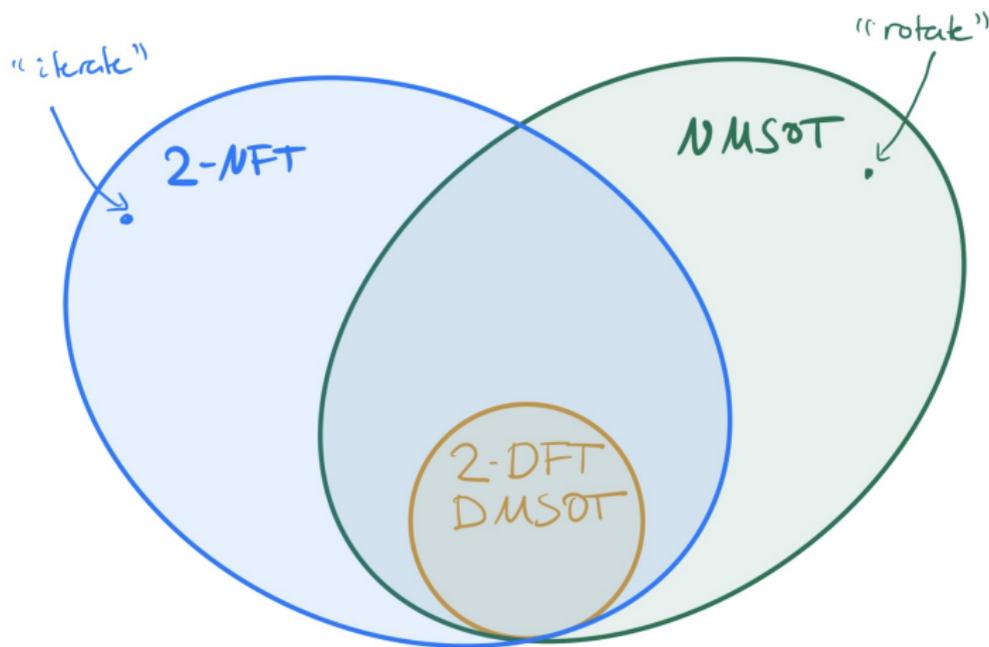
$$\varphi_\sigma^1(x) := \sigma(x), \quad \sigma \in \Sigma$$

$$\varphi_\sigma^2(x) := \sigma(x), \quad \sigma \in \Sigma$$

Overview: MSOT and 2-FT

Theorem (Engelfriet, Hogeboom 1988).

DMSOT and 2-DFT have the same expressive power. The classes of transductions defined by NMSOT and 2-NFT differ.



An Equivalent 1-way Model?

- ▶ The connection between MSO logic and finite automata is a cornerstone of the analysis of logical specifications.
- ▶ We have such a connection between MSO transductions and 2-way finite transducers.
- ▶ Unfortunately, reasoning with 2-way models can be quite technical and involved.
- ▶ Is there a 1-way model that expresses MSO definable transductions?
- ▶ Also, implementation-wise a 1-way model might be preferred.

Streaming String Transducers

A **Streaming String Transducer (SST)** is a finite automaton with a set \mathcal{X} of output registers. Transitions are additionally annotated with register updates, one for each register $X \in \mathcal{X}$, of the form

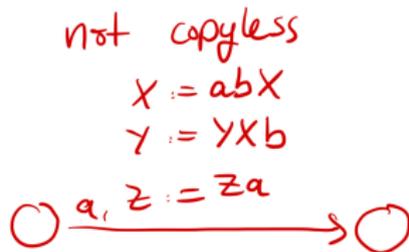
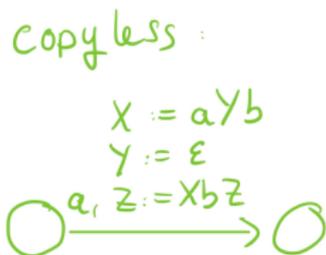
$$X := w_1 X_1 w_2 \cdots w_n X_n w_{n+1} \text{ with } X_i \in \mathcal{X} \text{ and } w_i \in \Sigma^*$$

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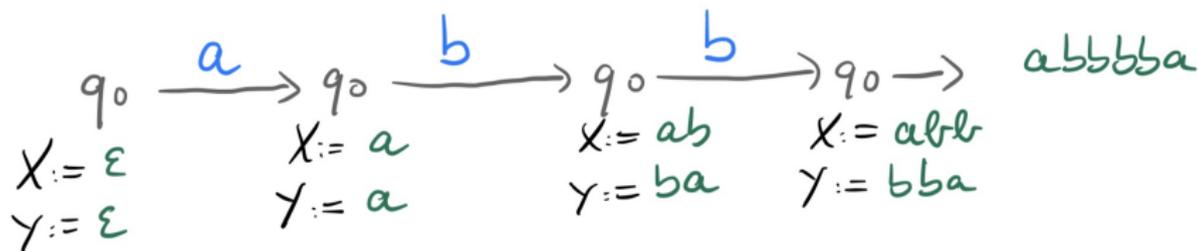
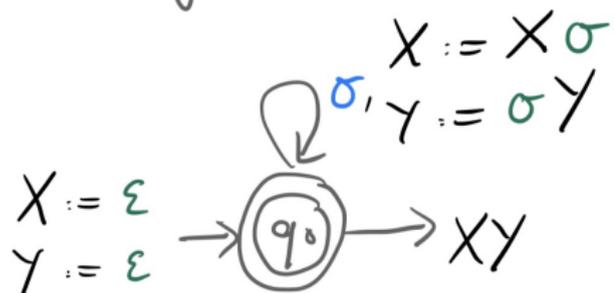
$$X := w_1 X_1 w_2 \cdots w_n X_n w_{n+1} \text{ with } X_i \in \mathcal{X} \text{ and } w_i \in \Sigma^*$$

Register updates are required to be **copyless**: each register appears at most once in the right-hand side of the updates in a transition.

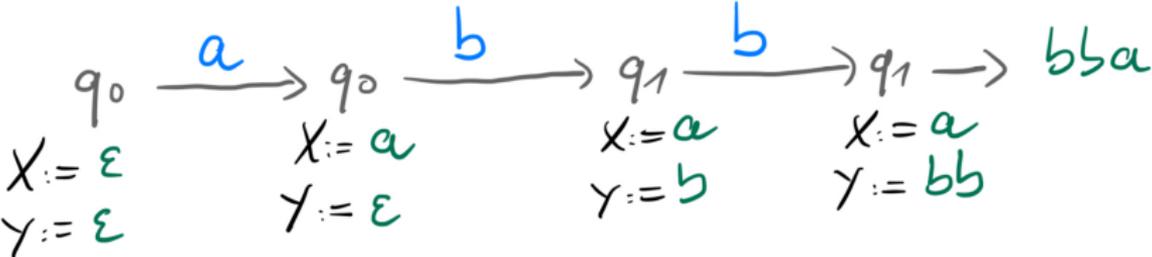
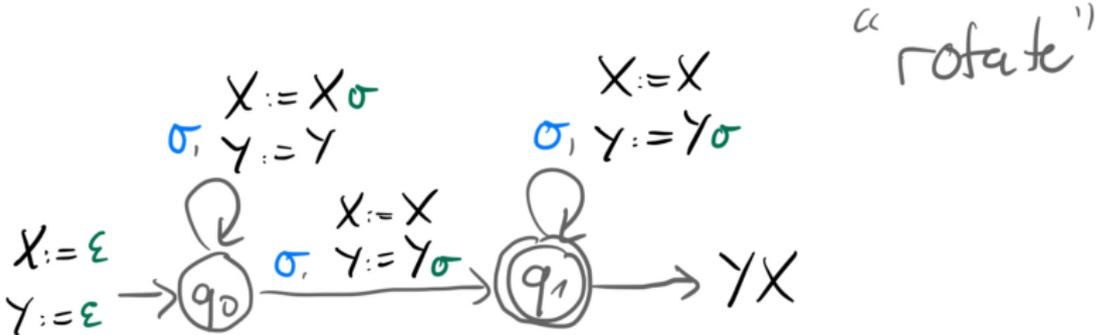


Example: Deterministic SST

"copy and reverse"

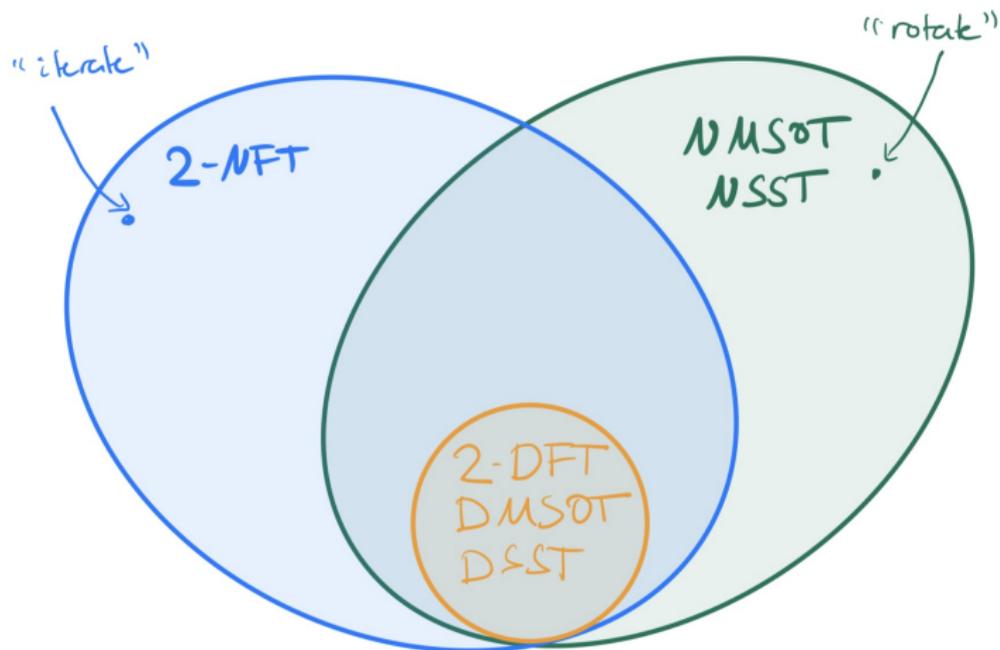


Example: Nondeterministic SST

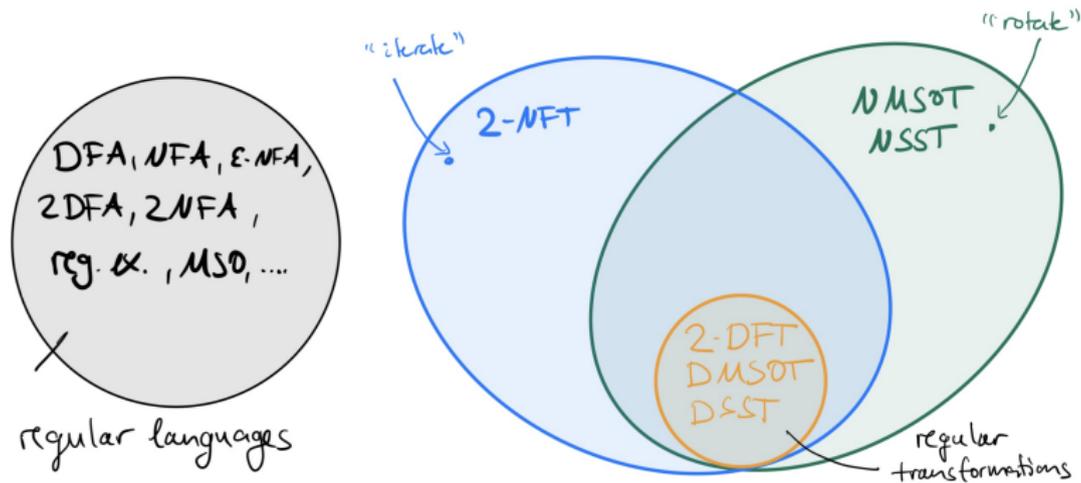


Overview: Adding SSTs

Theorem (Alur, Černy 2010; Alur, Deshmukh 2011). DMSOT and DSST have the same expressive power. So have NMSOT and NSST.



Languages vs. Transductions



Inbetween Functions and Relations

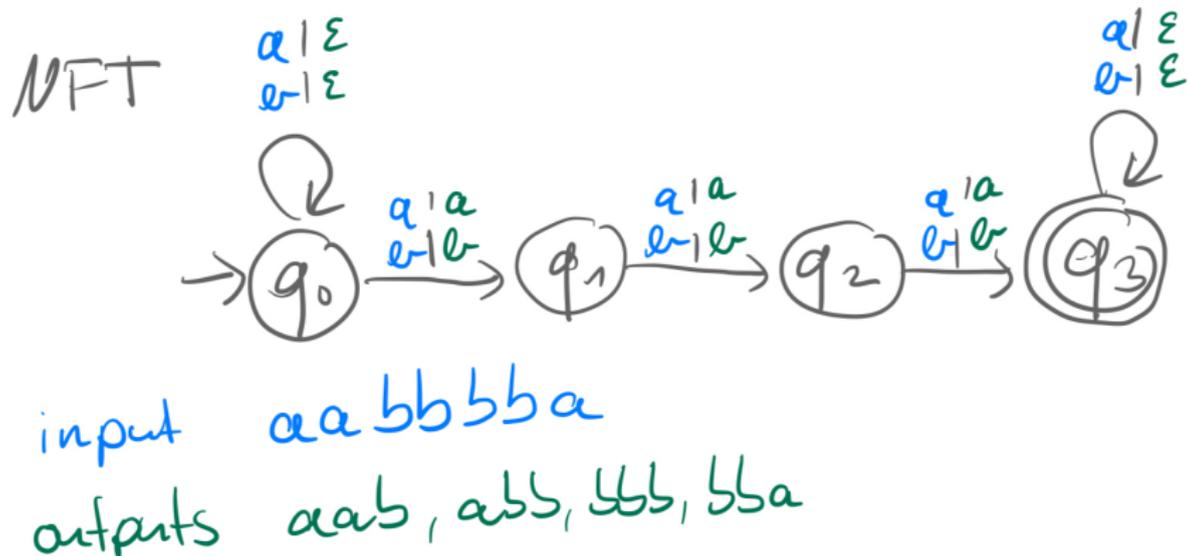
- ▶ Equivalence is decidable for 2-DFTs, DMSOTs, and DSSTs, while it is undecidable for their nondeterministic counter-parts.
- ▶ For NFTs, there is a robust subclass, namely NFTs defining finite-valued relations.
- ▶ Does this robustness extend to finite-valued relations defined by 2-NFTs, NMSOTs, NSSTs?

Finite-valued Transducers

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A transduction T is called **finite-valued** if there is a bound k such that T associates at most k outputs to each input.

Example.



Properties of Finite-valued FTs

A transduction T is called **finite-valued** if there is a bound k such that T associates at most k outputs to each input.

- ▶ Equivalence for finite-valued NFT is decidable (Culik, Karhumäki 1986).
- ▶ It is decidable if a given NFT is finite-valued (Weber 1990).
- ▶ Every k -valued NFT can be effectively decomposed into a union of k single-valued NFT (Weber 1993).

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- ▶ Every k -valued NFT can be effectively decomposed into a union of k single-valued NFT (Weber 1993).
- ▶ Decomposition allows for a new test for equivalence.

Given NFTs T_0, T finite-valued

check $T_0 \stackrel{?}{\subseteq} \bigcup_{i=1}^n T_i, T_i$ single-valued

What About Finite-valued SSTs?

NSST were introduced by (Alur, Deshmukh 2011). The authors raised the following questions:

- ▶ Is finite-valuedness of NSST decidable?
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- ▶ Can every finite-valued NSST be decomposed into a finite union of DSST?

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We give positive answers to all these questions and consequently obtain also results about finite-valued 2-NFTs and NMSOTs.

Results

Finite-valuedness

Theorem (FJLMPW 2024). It is decidable (PSPACE-complete) whether a nondeterministic SST is finite-valued.

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Decomposition

Theorem (FJLMPW 2024). Every k -valued SST can be effectively decomposed into a union of k deterministic SST.

Consequences of Decomposition Result

Together with a result of (Alur, Deshmukh 2011), we obtain:

Corollary. Equivalence for k -valued SST is decidable in elementary time.

Decidability was already known (Muscholl, Puppis 2019), but without an elementary upper complexity bound.

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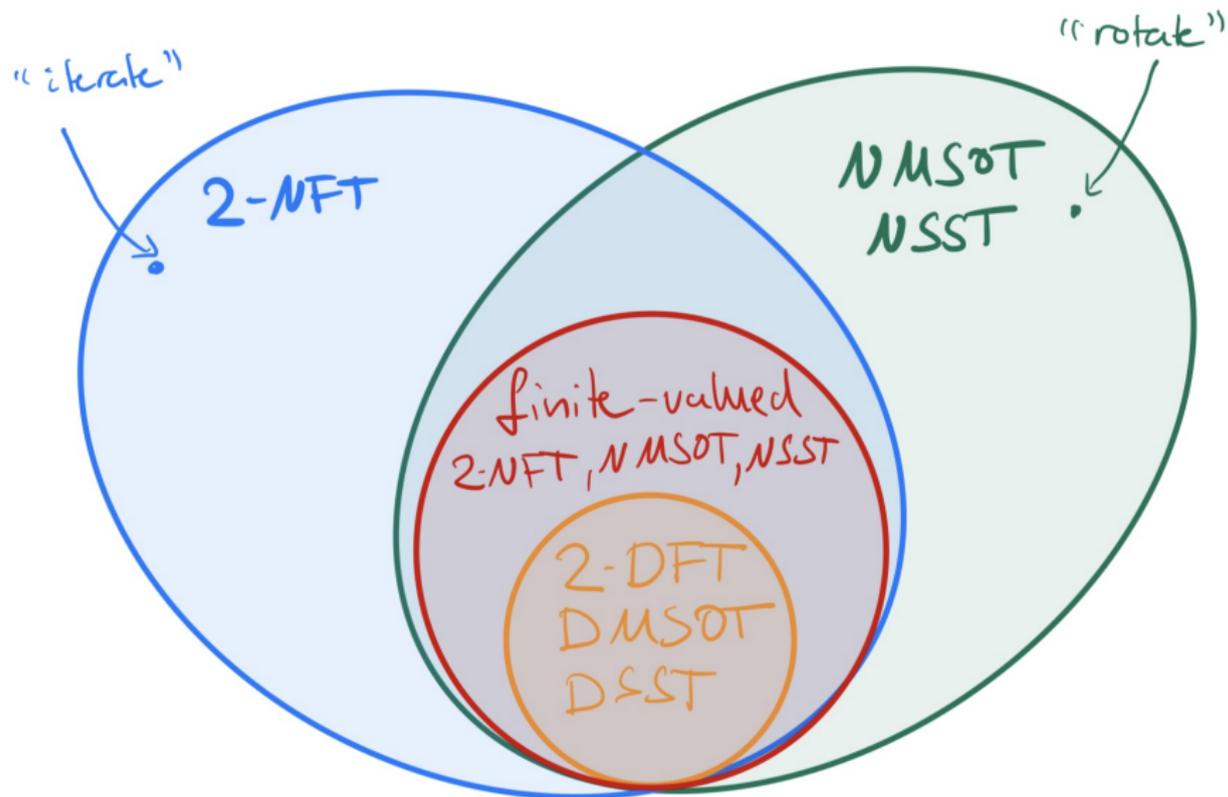
Corollary. Equivalence for k -valued SST is decidable in elementary time.

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Corollary. For finite-valued relations, the classes of 2-NFT, NSST, and NMSOT coincide.

The decomposition entails a translation from finite-valued NSST to 2-NFT. The other direction was already known (Alur, Černý 2011).

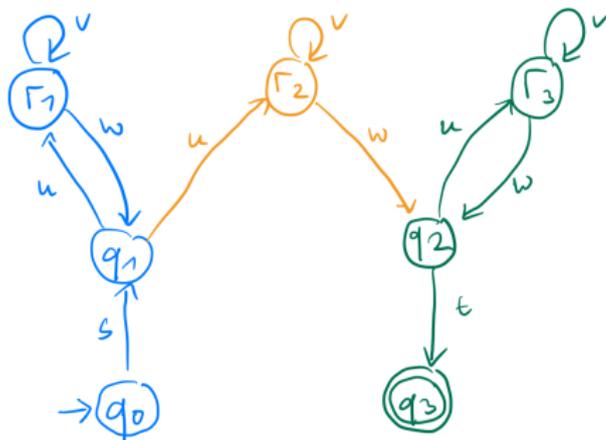
Overview: Adding Finite-valued Relations



Deciding Finite-valuedness

Characterization for Finite-Valuedness

Lemma. An SST is finite-valued iff it does not contain a “simply divergent W-pattern”.



Exist $n_1, \dots, n_5 \in \{1, 2\}$
 such that the runs below
 produce different outputs

$$\begin{aligned}
 q_0 &\xrightarrow{s} q_1 \xrightarrow{u v^{n_1} w} q_1 \xrightarrow{u v^{n_2} w} q_1 \xrightarrow{u v^{n_3} w} q_1 \xrightarrow{u v^{n_4} w} q_2 \xrightarrow{u v^{n_5} w} q_2 \xrightarrow{t} q_3 \\
 q_0 &\xrightarrow{s} q_1 \xrightarrow{u v^{n_1} w} q_1 \xrightarrow{u v^{n_2} w} q_2 \xrightarrow{u v^{n_3} w} q_2 \xrightarrow{u v^{n_4} w} q_2 \xrightarrow{u v^{n_5} w} q_2 \xrightarrow{t} q_3
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Differences between FTs and SSTs

Finite-valuedness is characterized for FTs and SSTs via “divergent W-patterns”. Main ingredients to establish the characterization are

- ▶ a pumping technique for loops, and
- ▶ comparing the “delay” between runs on the same input.

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This makes it necessary to develop a new pumping technique and a new notion of “delay”. A suitable notion of “delay” was introduced in (Filiot, Jecker, Löding, W. 2023).

Skeleton-idempotent Loops

The **skeleton** of an update $\alpha : \mathcal{X} \rightarrow (\Sigma \uplus \mathcal{X})^*$ is the update $\hat{\alpha} : \mathcal{X} \rightarrow \mathcal{X}^*$ obtained by removing all letters from Σ .

Skeletons and their composition form a finite monoid.

A **skeleton-idempotent loop** is a factor of a run that starts and ends in the same state and induces a skeleton-idempotent update (that is an update α so that α and $\alpha \cdot \alpha$ have the same skeleton).

Example.

$$\alpha : \begin{aligned} X_1 &:= a X_1 b X_2 c \\ X_2 &:= a \end{aligned}$$

$$\hat{\alpha} : \begin{aligned} X_1 &:= X_1 X_2 \\ X_2 &:= \varepsilon \end{aligned}$$

$$\alpha \cdot \alpha : \begin{aligned} X_1 &:= a \alpha(X_1) b \alpha(X_2) c = a a X_1 b X_2 c b a c \\ X_2 &:= a \end{aligned}$$

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$$\alpha^3: \begin{aligned} X_1 &:= a a a X_1 b X_2 c b a c b a c \\ X_2 &:= a \end{aligned}$$

Pumping Skeleton-idempotent Loops

Let α be a skeleton-idempotent update. For every $X \in \mathcal{X}$ there exist two words $u, v \in \Sigma^*$ such that

$$\alpha^n(X) = u^{n-1} \alpha(X) v^{n-1}.$$

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A Ramsey-type argument shows that in a long enough run a sequence of (pairwise disjoint) skeleton-idempotent loops occur.

Pumping Skeleton-idempotent Loops

Given a run with m such loops, pumping the i -th loop n_i times yields output of the form

$$w_0(u_1)^{k_1-1}w_1(u_2)^{k_2-1} \dots w_{r-1}(u_r)^{k_r-1}w_r,$$

where r is bounded by $2m|\mathcal{X}|$ and $k_1, \dots, k_r \in \{n_1, \dots, n_m\}$.

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α :	β :	γ
$X_1 := aX_1bX_2c$	$X_1 := X_1a$	$X_1 := X_1$
$X_2 := a$	$X_2 := ccX_2c$	$X_2 := X_2$
$X_3 := X_3b$	$X_3 := X_3$	$X_3 := X_3$

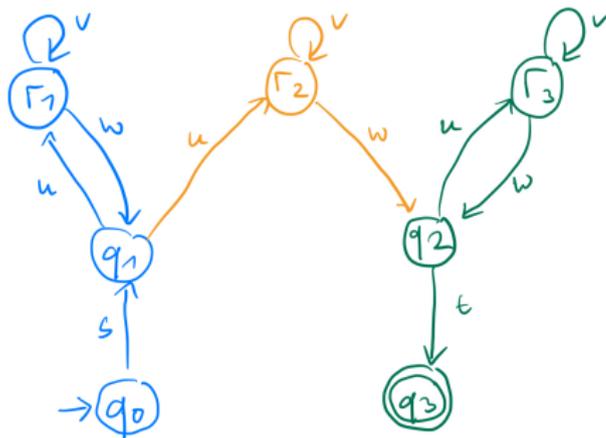
$\begin{matrix} a, \alpha & a, \beta \\ \circ & \circ \\ \rightarrow & \rightarrow \end{matrix} \xrightarrow{b, \gamma} X_1 X_2 X_3$

input $a^{n_1} b a^{n_2}$

$$\underbrace{(a)^{n_1-1} abc (bac)^{n_1-1} a (a)^{n_2-1}}_{X_1} \underbrace{(cc)^{n_2-1} ccac (c)}_{X_2} \underbrace{b (b)^{n_1-1}}_{X_3}$$

Pumping Skeleton-idempotent Loops

Goal: Use the “simply divergent W-pattern” to create a set of runs (via pumping) with the same input but different outputs.



Exist $n_1, \dots, n_5 \in \{1, 2\}$
 such that the runs below
 produce different outputs

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 q_0 &\xrightarrow{s} q_1 \xrightarrow{u^{n_1} v^{n_1} w} q_1 \xrightarrow{u^{n_2} v^{n_2} w} q_1 \xrightarrow{u^{n_3} v^{n_3} w} q_1 \xrightarrow{u^{n_4} v^{n_4} w} q_2 \xrightarrow{u^{n_5} v^{n_5} w} q_2 \xrightarrow{t} q_3 \\
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Word Inequalities

A **word inequality with parameters** is an inequality of two words in which repetitions of some subwords are parameterized by variables.

A **solution** is an assignment of numbers to the variables such that the resulting words are different.

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Example.

► $(ab)^x aa(b)^x abba \neq ababaa(bba)^x$ (one parameter)

The only non-solution is $x = 2$:

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$ababaabbabba =$
 $ababaabbabba$

- ▶ $b(ab)^y ab(b)^x \neq (ba)^x ba(b)^y b$ (two parameters)

Non-solutions are all choices such that $x = y$,

Solutions are all choices such that $x \neq y$.

Saarela and Consequences

Theorem (Saarela 2015). A word inequality with a single parameter x either has no solutions or the set of solutions is co-finite (the number of non-solutions is bounded by the number of occurrences of x in the inequality).

Saarela and Consequences

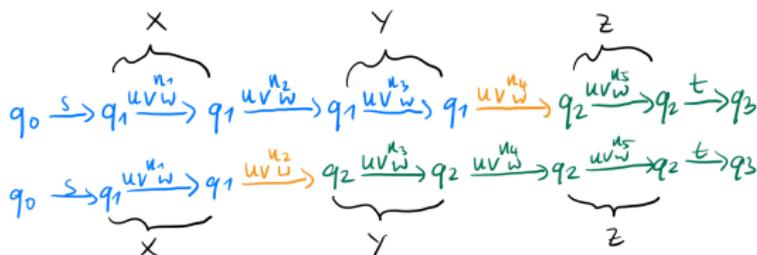
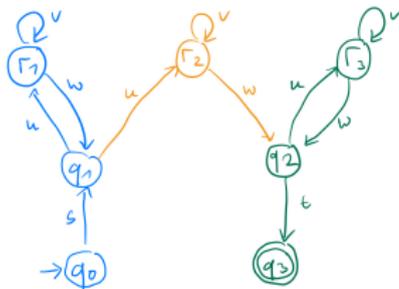
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Consequences

- ▶ We show properties of the solution space for word inequalities with multiple parameters.
- ▶ We show that if each inequality in a finite system of inequalities is solvable, then the system is solvable.

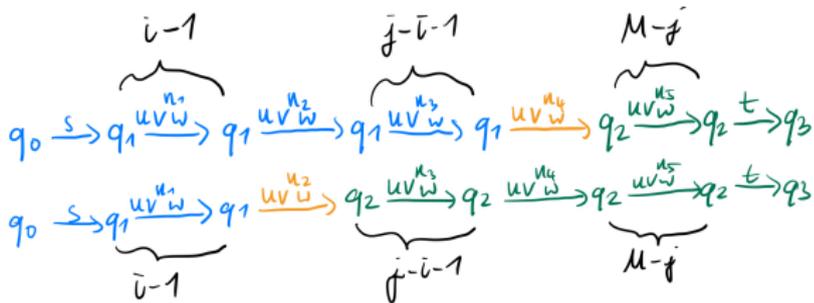
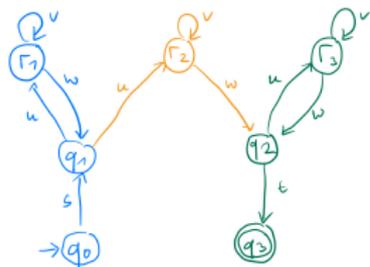
“simply divergent W-pattern” \Rightarrow not finite-valued

- ▶ Pattern yields two runs whose outputs have the right format for a word inequality with parameters x, y, z .

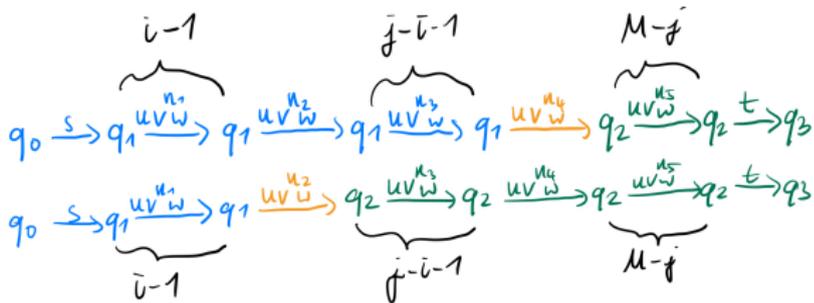
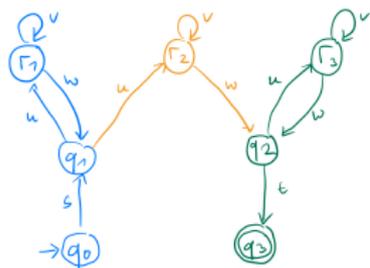


- ▶ Since there is one solution ($x = 1, y = 1, z = 1$), the set of solutions is infinite (and obeys some properties).
- ▶ We show that $(x = i - 1, y = j - i - 1, z = M - j)$ for all $i < j$ (with i, j from a specific set) for some arbitrarily large M is a solution.

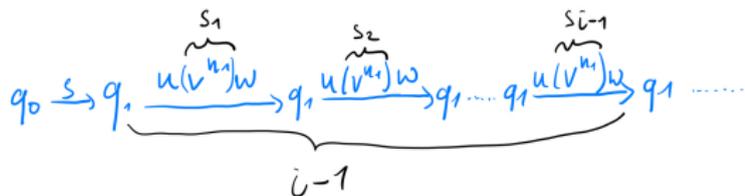
“simply divergent W-pattern” \Rightarrow not finite-valued



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- ▶ We now parameterize each v^{n1} in $(uv^{n1}w)^{i-1}$, each v^{n3} in $(uv^{n3}w)^{j-i-1}$, and each v^{n5} in $(uv^{n5}w)^{M-j}$.



- ▶ Iterating through all $i < j$ forms a finite system of word inequalities. It has a solution as each inequality has a solution.
- ▶ Each inequality is generated by a run with the same input. Hence, the SST is not finite-valued.

Summary

- ▶ We completed the picture for finite-valued SSTs concerning their expressive power and answered key decidability questions.
- ▶ Future work: Complexities are likely not optimal.

